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Feedback controller, which provides stabilization of the object around the nominal trajectory, can be designed using linearized model. Under assumption that the dynamic behavior of the object with ...

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from the field of classical control. This includes the transfer function, introduced in Chapter 8, which is a fundamental tool for understanding feedback systems. Using transfer functions, one can begin to analyze

the stability of feedback systems using frequency domain analysis, including the ability to reason about the closed

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Feedback Control of Dynamic Systems provides enough information, early and simply, so that a student can implement a controller in a digital computer, and an instructor can cover it in one lecture. This text is devoted to supporting students equally in their need to grasp both traditional and more modern topics of digital control.

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